

Preconditioning the Newton-Krylov method for reactive transport

Michel Kern, L. Amir, A. Taakili

INRIA Paris-Rocquencourt — Maison de la Simulation

MoMaS workshop
Reactive Transport Modeling in the Geological Sciences
Institut Henri Poincaré November 2015



- 1 Model and formulation
- 2 Elimination and preconditioning
- 3 Application to MoMaS benchmark

Study algorithms for reactive transport that

- 1 Keep chemistry and transport codes **separate**
- 2 Allow **strong** numerical coupling

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Model setup

One phase reactive transport of N_s species, undergoing N_r reactions

Transport operator $L\mathbf{c} = \nabla \cdot (u\mathbf{c} - D\nabla\mathbf{c})$ on $\omega \subset \mathbf{R}^d$, $d = 1, 2, 3$. u Darcy velocity, D diffusion dispersion tensor.

Chemical system Aqueous and sorption reactions, all equilibrium.

$$S \begin{pmatrix} X \\ \bar{X} \end{pmatrix} = \begin{pmatrix} S_{cc} & 0 \\ S_{\bar{c}\bar{c}} & S_{\bar{c}c} \end{pmatrix} \begin{pmatrix} X \\ \bar{X} \end{pmatrix} \rightleftharpoons \begin{pmatrix} 0 \\ 0 \end{pmatrix},$$

Model setup

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Mass conservation

$$\phi \partial_t c + Lc = S_{cc}^T r + S_{\bar{c}\bar{c}}^T \bar{r},$$

$$\phi \partial_t \bar{c} = S_{\bar{c}\bar{c}}^T \bar{r},$$

Mass action laws

$$\begin{pmatrix} S_{cc} & 0 \\ S_{\bar{c}\bar{c}} & S_{\bar{c}\bar{c}} \end{pmatrix} \begin{pmatrix} \log c \\ \log \bar{c} \end{pmatrix} = \begin{pmatrix} \log K \\ \log \bar{K} \end{pmatrix},$$

Elimination of equilibrium rates: coupled problem

The kernel matrix (after Saaltink et al (98))

$$U \text{ st } US^T = 0, U = \begin{pmatrix} U_{cc} & U_{c\bar{c}} \\ 0 & U_{\bar{c}\bar{c}} \end{pmatrix}, \quad \begin{aligned} \phi \partial_t (U_{cc} \mathbf{c} + U_{c\bar{c}} \bar{\mathbf{c}}) + U_{cc} L \mathbf{c} &= 0 \\ \phi \partial_t U_{\bar{c}\bar{c}} \bar{\mathbf{c}} &= 0. \end{aligned}$$

Transformation

$$\begin{aligned} T &= U_{cc} \mathbf{c} + U_{c\bar{c}} \bar{\mathbf{c}} = T_I + T_S \\ \bar{T} &= U_{\bar{c}\bar{c}} T_S \end{aligned}$$

Coupled system

$$\begin{aligned} \phi \partial_t T_I + \phi \partial_t T_S + L T_I &= 0 \\ \phi \partial_t \bar{T} &= 0. \end{aligned}$$

Completed by mass action laws

System of non linear equations

Mass action law $\hat{S} \log \left(\frac{c}{\bar{c}} \right) = \log \left(\frac{k}{\bar{k}} \right)$

Mass conservation $Uc + \bar{U}\bar{c} = T$ T known from transport

Take concentration **logarithms** as main unknowns

Use **globalized** Newton's method (line search, trust region).

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Role of chemical model

Given total T , split into

Liquid $T_l = Uc$,

Solid $T_s = \bar{U}\bar{c}$

total concentrations

Result of chemical problem

$$T_s = \Psi_c(T)$$

A note on solving the equilibrium system

Chemical system

$$S \log \mathbf{c} = \log K, \quad U \mathbf{c} = T$$

Using QR factorization of $S^T = (Q_1 \quad Q_2) \begin{pmatrix} R_1 \\ 0 \end{pmatrix}$ gives $U = Q_2$.

Write $\mathbf{z} = \log \mathbf{c} = Q_1 \mathbf{z}_1 + Q_2 \mathbf{z}_2$, mass action law gives $R_1^T \mathbf{z}_1 = \log K$.

Non linear system becomes

$$Q_2^T \exp(Q_1 \mathbf{z}_1 + Q_2 \mathbf{z}_2) = T$$

Only unknown is \mathbf{z}_2 (size $N_s - N_r$). Recover **primary** and **secondary** species !
Jacobian is

$$J_c = Q_2^T \mathbf{C} Q_2, \text{ with } \mathbf{C} = \text{diag}(\mathbf{c}) = \text{diag}(\exp(\mathbf{z})).$$

Source of ill-conditioning is \mathbf{C} (cf. J. Carrayrou).

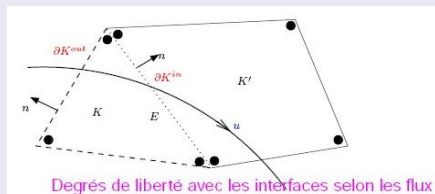
Solution of transport by operator splitting

See Chavent-Jaffré, Ackerer et al., Putti et al., Arbogast et al., ...

Advection step

Explicit, finite volumes

- Locally mass **conservative**
- Allows **unstructured** mesh
- CFL condition: use **sub-time-steps**



Dispersion step

Mixed finite elements (implicit)

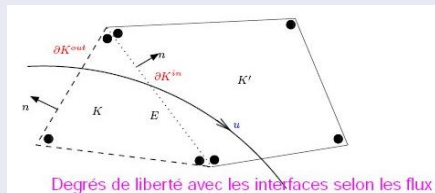
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Condense transport solver, one time step

$$\underbrace{(M + \Delta t L)}_A C^{n+1} = M C^n + \Delta t f^n \Leftrightarrow C^{n+1} = \Psi_T(f^n, C^n)$$

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- + easy to program, code reuse
- - not robust, small time steps

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(Try to) use best of SI and DS

A global method from the fixed-point formulation (1)

Discrete non-linear system

$$\begin{cases} AT_l^{n+1} + MT_s^{n+1} = \underbrace{M(T_l^n + T_s^n)}_{b^n} \\ T_s^{n+1} - \Psi_C(T_l^{n+1} + T_s^{n+1}) = 0 \end{cases}$$

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Elimination of T_i

$$F_2(T_s) = T_s^{n+1} - \Psi_C(T_s^{n+1} - A^{-1}MT_s^{n+1} + A^{-1}b^n) = 0$$

Can be solved by block Gauss-Seidel or by **Newton's** method

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Residual computation

- 1 Apply Ψ_T : solve **transport** for each species,
- 2 Apply Ψ_C : solve **chemistry** for each grid cell.

A global method from the fixed-point formulation (2)

- + **Non-intrusive** approach
- + **Precipitation** can be included
- – One chemical equilibrium **solve** for each function evaluation

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Solution by **Newton-Krylov** method

- Solve the linear system by an **iterative** method (GMRES)
- Requires only jacobian matrix by vector products, Jacobian not stored
- Keep transport and chemistry as black boxes
- Used for CFD, shallow water, radiative transfer(Keyes, Knoll, JCP 04), and for reactive transport (Hammond et al., Adv. Wat. Res. 05)

Inexact Newton framework

Approximation of the Newton's direction $\|f'(x_k)d + f(x_k)\| \leq \eta_k \|f(x_k)\|$
adaptive choice of **the forcing** term η_k (Kelley, Eisenstat and Walker)

L. Amir, MK (Comp. Geosci. 09)

Coupled formulation

Jacobian with block structure

$$J = \begin{pmatrix} A & M \\ -D & I - D \end{pmatrix}$$

D is Jacobian of chemistry operator (cf. Knabner et al.: resolution function),
computed implicitly

Inverting Jacobian ; solve transport

Elimination of T_i

Jacobian of F_2 : $J_2 = I - D + DA^{-1}M$.

Computing Jacobian: solve transport. Solve cannot use matrix form (GMRES OK)

Preconditioning

- Essential for good linear performance
- Difficult for matrix free formulation
- Block preconditioners preserve problem structure

Jacobi

$$P_{\text{Jac}} = \begin{pmatrix} A & 0 \\ 0 & I - D \end{pmatrix}$$

$$P_{\text{Jac}}^{-1} J = \begin{pmatrix} I & A^{-1} M \\ -(I - D)^{-1} D & I \end{pmatrix}$$

Gauss-Seidel

$$P_{\text{GS}} = \begin{pmatrix} A & 0 \\ -D & (I - D) \end{pmatrix}$$

$$P_{\text{GS}}^{-1} J = \begin{pmatrix} I & A^{-1} M \\ 0 & (I - D)^{-1} (I - D + DA^{-1} M) \end{pmatrix}$$

Elimination of T_i equivalent to Schur comp. of Gauss-Seidel.

Field of value analysis

GMRES convergence **not** determined by eigenvalues (Greenbaum et al. 96)

$W(A) \equiv \{x^*Ax \mid x \in \mathbb{C}^n, \|x\| = 1\}$, convex set, contains eigenvalues of A

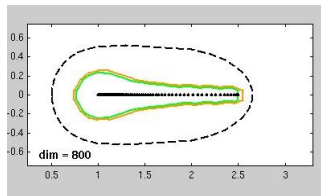
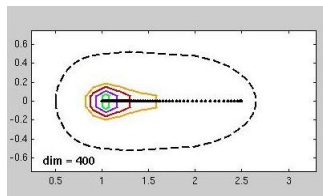
$$\|r_k\|_2 \leq 2 \min_{p \in \mathcal{P}_k^*} \max_{z \in W(A)} |p(z)| \|r_0\|_2.$$

Simplified system: one species with sorption

$$\Lambda(P_{\text{Jac}}^{-1}J) \subset [1 - iCh, 1 + iCh]$$

$$\Lambda(J_2) \subset [1, 1 + Ch^2]$$

Bounded away from 0 independently of h .



Eigenvalues, field of values and pseudospectrum for GS preconditioning



Preconditioner performance

1D model (Matlab + Sundials), $h = 0.05$, $K_L = 1.$, $\sigma = 1.5$, and $\Delta t = 0.0135$.

Mesh dependence : **constant** forcing term

	h		$h/2$		$h/4$		$h/8$	
	NI	LI	NI	LI	NI	LI	NI	LI
None	3	104	3	167	3	267	3	453

Mesh dependence : **adaptive** forcing term

	h		$h/2$		$h/4$		$h/8$	
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NI: # nonlinear iters, NLI: total # linear iters.

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BGS	8	23	7	24	7	22	8	25
Elimination	5	15	5	15	5	15	5	15

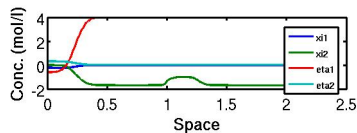
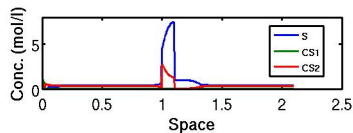
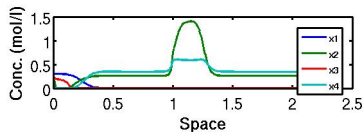
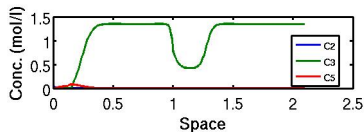
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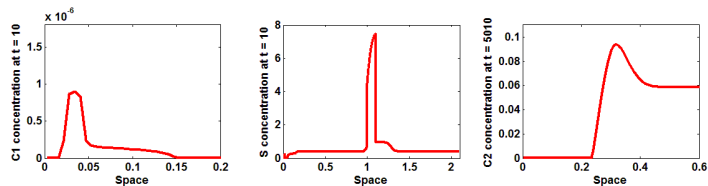
MoMaS benchmark (easy, 1D)

- 9 liquid, 3 sorbed primary species.
- Huge variation in equilibrium constants, large stoichiometric coeffs.
- Long simulation time
- Set-up by J. Carrayrou, MK, P. Knabner (Comp. Geo. 2009)

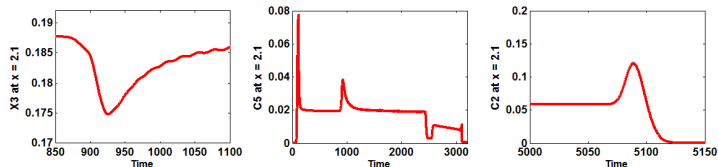
Species concentrations, $t = 10$



Concentration profiles



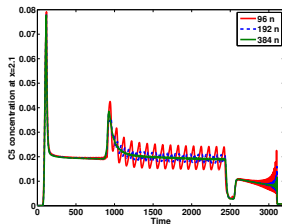
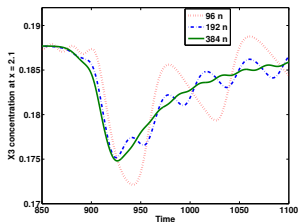
Left: C_1 at $t = 10$, middle: S at $t = 10$, right: C_2 at $t = 5010$



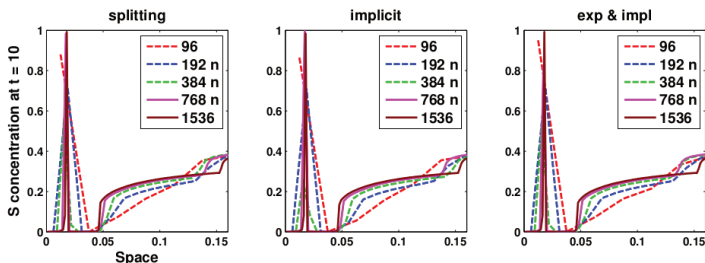
Concentrations at right end of the domain as a function of time.

Left: X3, middle: C5, right: C2

Accuracy, spatial discretization

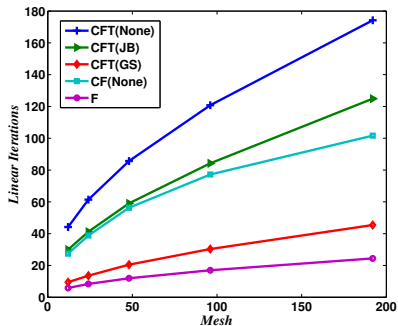
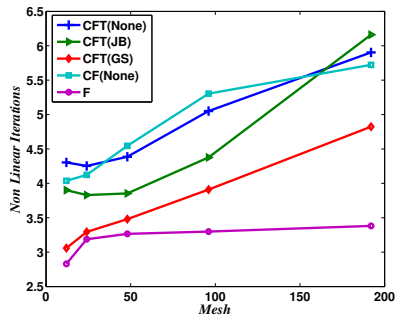


Elution curves: left X_3 , right C_5



Concentration of species S at $t=10$, different schemes

Comparison of preconditioning strategies



Left: Non-linear iterations, right: linear iterations