

Polymerization Models for Prion

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BANG day, 22 september 2009

Outline

- 1 First Model
- 2 The PMCA
 - Principle and Model
 - Two Optimization Problems
- 3 New model
 - Presentation
 - Numerical Study

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Biological Model

The pathogenic agent is an abnormal protein present as aggregates :

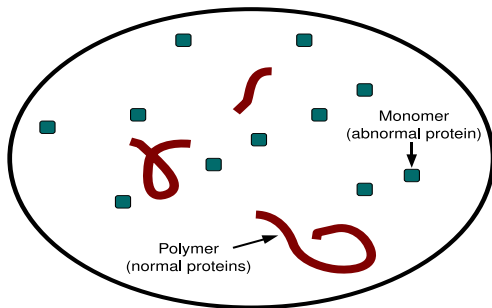


Fig.: Infected cell.

Equations

Model of Greer *et al.* (2006), Calvez *et al.* (2008), Doumic *et al.* (2009) :

$$\left\{ \begin{array}{l} \frac{dV(t)}{dt} = \lambda - V(t) \left[\gamma + \int_0^{\infty} \tau(x) u(x, t) dx \right], \\ \frac{\partial}{\partial t} u(x, t) = -V(t) \frac{\partial}{\partial x} (\tau(x) u(x, t)) - [\mu(x) + \beta(x)] u(x, t) \\ \quad + 2 \int_x^{\infty} \beta(y) \kappa(x, y) u(y, t) dy, \\ u(0, t) = 0, \\ u(x, 0) = u_0(x). \end{array} \right.$$

$V(t)$: quantity of monomers at time t ,

$u(x, t)$: quantity of polymers of size x at time t .

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The PMCA (Protein Misfolded Cyclic Amplification) is a protocole which allows to increase *in vitro* the prion quantity of a sample. It consists in the repeated alternation of two phases :

- 1 **Incubation** during which the polymerization is promoted
- 2 **Sonication** which increases a lot the fragmentation

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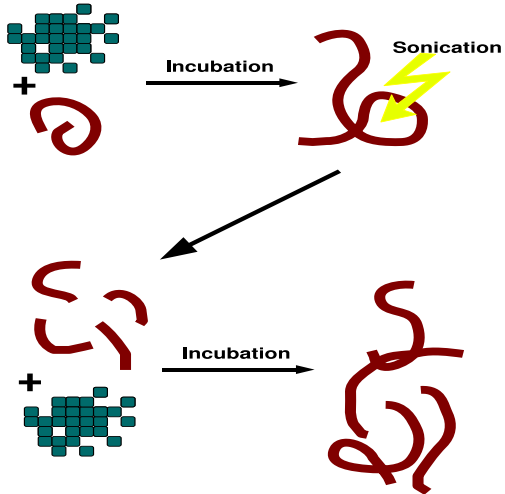


Fig.: PMCA principle.

We model the sonication multiplying the fragmentation $\beta(x)$ by a parameter $\alpha(t)$:

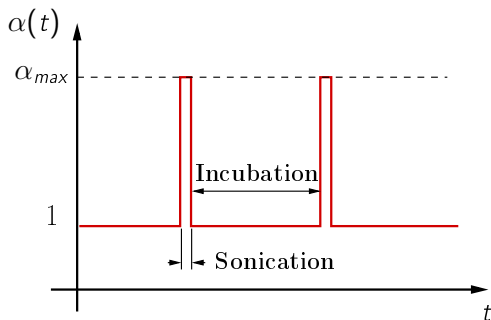
$$\frac{\partial}{\partial t} u(x, t) = -\frac{\partial}{\partial x} (\tau(x) u(x, t)) - \beta(x) u(x, t) + 2 \int_x^\infty \beta(y) \kappa(x, y) u(y, t) dy,$$

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α constant

(with V. Calvez and M. Doumic)

For a constant sonication $\alpha(t) \equiv \alpha$, there exists a principal eigenvalue λ_α for the equation :

Existence of Eigenlements for a General Aggregation-Fragmentation Model, M. Doumic et P. G., to appear in M3AS.

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Theorem : Existence of α_{opt} (V. Calvez, M. Doumic, P. G.)

If the polymerization rate τ satisfies

- $\tau(0) = 0$ and τ is convex in a neighborhood of 0,
- $\tau(x) = o(x)$ when x tends to $+\infty$,

Then there exists a α_{opt} such that $\lambda_\alpha \leq \lambda_{\alpha_{opt}}$ for all $\alpha > 0$.

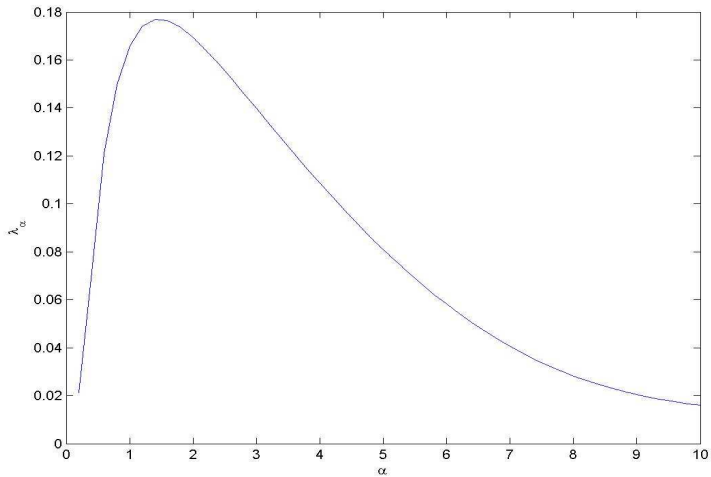


Fig.: Existence of an optimal α .

Any α

(with V. Calvez)

For a given outlook T , we search a control $\alpha : [0, T] \rightarrow [1, \alpha_{max}]$ which maximizes the mass obtained at the final time T . For this we come back to a discrete in size model :

$$\begin{cases} \frac{du_i}{dt} = -\tau_i(u_i - u_{i-1}) - \alpha(t)\beta_i u_i + 2 \sum_{j=i+1}^n \alpha(t)\beta_j \kappa_{i,j} u_j , \\ u_i(0) = u_i^0 , \end{cases}$$

for all $1 \leq i \leq n$. Then we search to optimize $\sum_{i=1}^n i u_i(T)$.

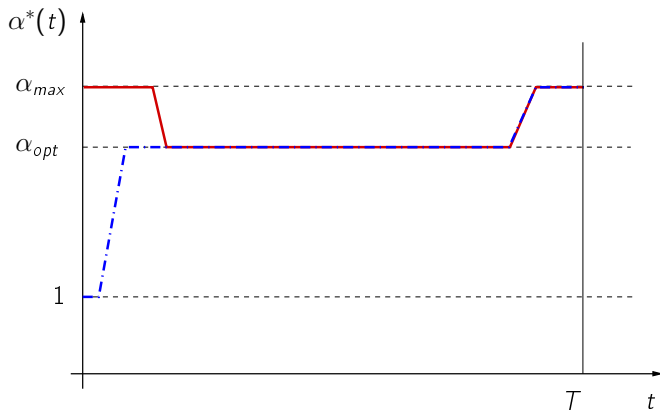


Fig.: Profiles of $\alpha^*(t)$ when $1 < \alpha_{opt} < \alpha_{max}$.

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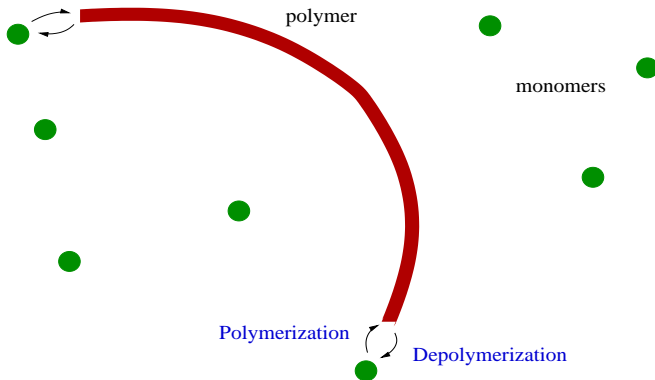


Fig.: Polymerization-depolymerization

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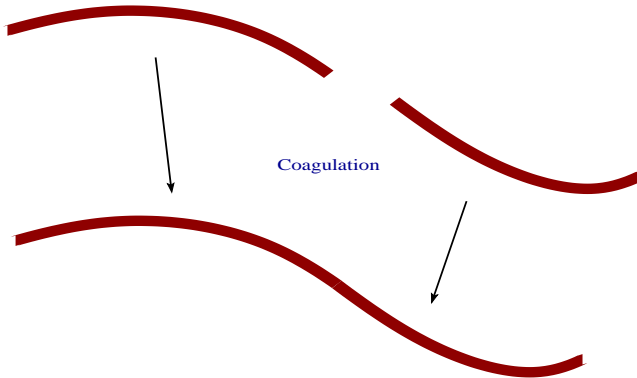


Fig.: Coagulation of two polymers

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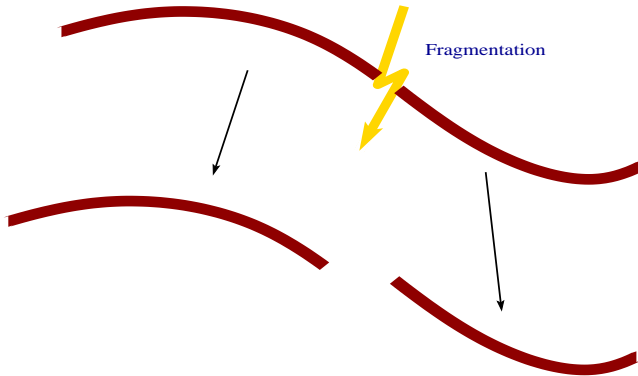


Fig.: Fragmentation of a polymer

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with F. Charles, M. Doumic, N. Lenuzza, H. Rezaei

$$\left\{ \begin{array}{l} \frac{dV(t)}{dt} = \int_0^\infty \left(-V(t)k_{on}(x) + k_{off}(x) \right) c(x, t) dx, \\ \frac{\partial}{\partial t} c(x, t) = -\frac{\partial}{\partial x} \left((V(t)k_{on}(x) - k_{off}(x))c(x, t) \right) \\ \quad - c(x, t) \int_0^x k_{frag}(y, x) dy + 2 \int_x^\infty k_{frag}(x, y) c(y, t) dy \\ \quad + \frac{1}{2} \int_0^x c(y, t)c(x-y, t)k_{coag}(y, x-y) dy \\ \quad - c(x, t) \int_0^\infty c(y, t)k_{coag}(x, y) dy, \\ c(0, t) = 0, \quad c(x, 0) = c_0(x) \quad \text{and} \quad V(0) = V_0. \end{array} \right.$$

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- Newton-Cotes 5 or Milne for integral terms
- RK3 for the time evolution

Simulations (comparison WENO/Upwind)

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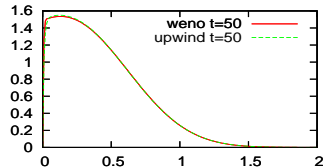
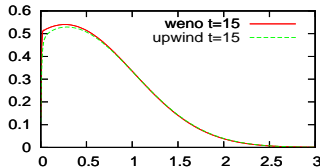
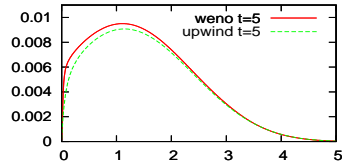
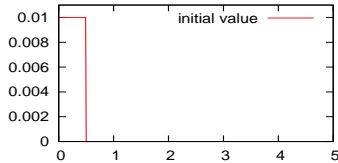


Fig.: Evolution of the size repartition