

## [Help](#)

```
#include "
href../../../../mod/nig1d/nig1d_pad/nig1d_pad_h_src.pdfnig1d_pad.h"
#include "pnl/pnl_cdf.h"
#include "pnl/pnl_random.h"
#include "pnl/pnl_specfun.h"
// #include "pnl_bessel.h"
#include "pnl/pnl_mathtools.h"
#include "pnl/pnl_random.h"
#include "pnl/pnl_specfun.h"
#include "pnl/pnl_mathtools.h"

#if defined(PremiaCurrentVersion) && PremiaCurrentVersion < (2011+2) //The "#els
static int CHK_OPT(MC_Nig_Fixed)(void *Opt, void *Mod)
{
    return NONACTIVE;
}
int CALC(MC_Nig_Fixed)(void *Opt, void *Mod, PricingMethod *Met)
{
    return AVAILABLE_IN_FULL_PREMIA;
}
#else
//Compute the positive or negative jump size between the smallest and the bigges
static double jump_generator_NIG(double *cdf_jump_vect, double *cdf_jump_points,
{
    double z, v, y;
    int test, temp, l, j, q;
    test = 0;
    v = pnl_rand_uni(generator);
    y = cdf_jump_vect[cdf_jump_vect_size] * v;
    l = cdf_jump_vect_size / 2;
    j = cdf_jump_vect_size;
    z = 0;
    if (cdf_jump_vect[l] > y)
    {
        l = 0;
        j = cdf_jump_vect_size / 2;
    }
    if (v == 1)
    {
```

```

        z = cdf_jump_points[cdf_jump_vect_size];
    }
    if (v == 0)
    {
        z = cdf_jump_points[0];
    }
    if (v != 1 && v != 0)
    {
        while (test == 0)
        {
            if (cdf_jump_vect[l + 1] > y)
            {
                q = l;
                test = 1;
            }
            else
            {
                temp = (j - l - 1) / 2 + l;
                if (cdf_jump_vect[temp] > y)
                {
                    j = temp;
                    l = l + 1;
                }
                else
                {
                    l = temp * (temp > l) + (l + 1) * (temp <= l);
                }
            }
        }
        z = pow(1. / cdf_jump_points[q] - (y - cdf_jump_vect[q]) * exp(-beta * cdf_jump_vect[q]), 1 / beta);
    }
    return z;
}

```

```

static int NIG_Mc_Fixed(double s_maxmin, NumFunc_2 *P, double S0, double T, double K,
{
    double eps, s, s1, s2, s3, s4, s5, s6, sup, inf, infS, supS, payoff, control,
    double sigma0, lambda_p, control_expec, lambda_m, cdf_jump_bound, pas, *t, cov,
    double var_control, cor_payoff_control, control_coef, var_proba, *cdf_jump_points,
    double *cdf_jump_vect_m, *X, tau, *jump_time_vect_p, *jump_time_vect_m, *W, s0
}

```

```

int i, j, k, jump_number_p, jump_number_m, m1, m2, cdf_jump_vect_size, *N_p, *
K = P->Par[0].Val.V_DOUBLE;
n_int = 10000;
discount = exp(-r * T);
err = 1E-16;
eps = 0.1;
beta1 = 0; //0.5826;
cdf_jump_vect_size = 100000;
X = malloc((n_points + 1) * sizeof(double));
W = malloc((n_points + 1) * sizeof(double));
t = malloc((n_points + 1) * sizeof(double));
N_p = malloc((n_points + 1) * sizeof(int));
N_m = malloc((n_points + 1) * sizeof(int));
X[0] = 0;
W[0] = 0;
pas = T / n_points;
for (i = 0; i <= n_points; i++)
{
    t[i] = i * pas;
}
N_p[0] = 0;
N_m[0] = 0;
control_expec = exp((r - divid) * T);
s = 0;
s1 = 0;
s2 = 0;
s3 = 0;
s4 = 0;
s5 = 0;
s6 = 0;
alpha = sqrt(theta * theta + sigma * sigma / kappa) / (sigma * sigma);
beta = theta / (sigma * sigma);
delta = sigma / sqrt(kappa);
if (alpha - fabs(beta) < 1)
{
    fprintf(stderr, "Function NIG_Mc_Fixed: invalid parameters. We must have s
}
while (delta * exp(-fabs(beta)*eps) / (M_PI * eps) < 17)
    eps = eps * 0.9;
////////////////////////////////////
cdf_jump_bound = 1;

```

```

//Computation of the biggest jump that we tolerate
while (2 * sqrt(alpha / (2 * M_PI))*delta * exp(-(alpha - fabs(beta))*cdf_jump
    cdf_jump_bound++;
pas = (cdf_jump_bound - eps) / cdf_jump_vect_size;
cdf_jump_points = malloc((cdf_jump_vect_size + 1) * sizeof(double));
cdf_jump_vect_p = malloc((cdf_jump_vect_size + 1) * sizeof(double));
cdf_jump_vect_m = malloc((cdf_jump_vect_size + 1) * sizeof(double));
cdf_jump_points[0] = eps;
cdf_jump_vect_p[0] = 0;
cdf_jump_vect_m[0] = 0;
//computation of the cdf of the positive and negative
//jumps at some points
for (i = 1; i <= cdf_jump_vect_size; i++)
{
    cdf_jump_points[i] = i * pas + eps;
    cdf_jump_vect_p[i] = cdf_jump_vect_p[i - 1] + exp(beta * cdf_jump_points[i]
    cdf_jump_vect_m[i] = cdf_jump_vect_m[i - 1] + exp(-beta * cdf_jump_points[i]
}
////////////////////////////////////
lambda_p = cdf_jump_vect_p[cdf_jump_vect_size] * alpha * delta / M_PI;
lambda_m = cdf_jump_vect_m[cdf_jump_vect_size] * alpha * delta / M_PI;
sigma0 = 0;
for (i = 1; i <= n_int; i++)
    sigma0 += (eps * i / n_int) * cosh(beta * i * eps / n_int) * pnl_bessel_k(1.
sigma0 = sqrt(sigma0 * alpha * delta * 2 / M_PI);
drift = 0;
for (i = 1; i <= n_int; i++)
    drift += sinh(beta * i * eps / n_int) * pnl_bessel_k(1., alpha * i * eps / n
drift = drift * alpha * delta * 2 / M_PI + (r - divid) - delta * (sqrt(alpha *
////////////////////////////////////
m1 = (int)(1000 * lambda_p * T);
m2 = (int)(1000 * lambda_m * T);
jump_time_vect_p = malloc((m1) * sizeof(double));
jump_time_vect_m = malloc((m2) * sizeof(double));
jump_time_vect_p[0] = 0;
jump_time_vect_m[0] = 0;
////////////////////////////////////
pnl_rand_init(generator, 1, n_paths);
if ((P->Compute) == &Call_OverSpot2)
{
    s_maxmin = MAX(s_maxmin, K);

```

```

s_maxmin = exp(-beta1 * sigma0 * sqrt(T / n_points)) * s_maxmin; //shifting
for (i = 0; i < n_paths; i++)
{
    //simulation of the positive jump times and number
    tau = -1 / (lambda_p) * log(pnl_rand_uni(generator));
    jump_number_p = 0;
    while (tau < T)
    {
        jump_number_p++;

        jump_time_vect_p[jump_number_p] = tau;
        tau += -1 / (lambda_p) * log(pnl_rand_uni(generator));
    }

    //simulation of the negative jump times and number
    tau = -1 / (lambda_m) * log(pnl_rand_uni(generator));
    jump_number_m = 0;
    while (tau < T)
    {
        jump_number_m++;
        jump_time_vect_m[jump_number_m] = tau;
        tau += -1 / (lambda_m) * log(pnl_rand_uni(generator));
    }
    jump_time_vect_p[jump_number_p + 1] = 0;
    jump_time_vect_m[jump_number_m + 1] = 0;
    //////////////////////////////////////

    // simulation of one NIG path
    for (k = 1; k <= n_points; k++)
    {
        W[k] = sigma0 * pnl_rand_normal(generator) * sqrt(t[k] - t[k - 1])
        N_p[k] = N_p[k - 1];
        j = N_p[k - 1] + 1;
        while (jump_time_vect_p[j] <= t[k] && j <= jump_number_p)
        {
            N_p[k]++;
            j++;
        }
        s0 = 0;
        for (j = N_p[k - 1] + 1; j <= N_p[k]; j++)
            s0 += jump_generator_NIG(cdf_jump_vect_p, cdf_jump_points, cdf_j

```

```

N_m[k] = N_m[k - 1];
j = N_m[k - 1] + 1;
while (jump_time_vect_m[j] <= t[k] && j <= jump_number_m)
{
    N_m[k]++;
    j++;
}
for (j = N_m[k - 1] + 1; j <= N_m[k]; j++)
    s0 -= jump_generator_NIG(cdf_jump_vect_m, cdf_jump_points, cdf_j
X[k] = X[k - 1] + (W[k] - W[k - 1]) + s0;
}
////////////////////////////////////
//computation of the supremum and the infimum of the NIG path
inf = X[0];
sup = X[0];
for (j = 1; j <= n_points; j++)
{
    if (inf > X[j])
        inf = X[j];
    if (sup < X[j])
        sup = X[j];
}
proba = 0;
supS = S0 * exp(sup);
if (supS < s_maxmin)
{
    supS = s_maxmin;
    proba = 1.;
}
payoff = supS;
supS = S0 * exp(X[n_points] - inf); //antithetic variable associated w
if (supS < s_maxmin)
{
    supS = s_maxmin;
    proba += 1.;
}
proba = proba / 2;
payoff = discount * (payoff + supS) / 2;
control = exp(X[n_points]);
s += control;
s1 += payoff;

```

```

        s2 += payoff * payoff;
        s3 += control * payoff;
        s4 += control * control;
        s5 += proba;
        s6 += proba * proba;
    }
    cov_payoff_control = s3 / n_paths - s1 * s / ((double)n_paths * n_paths);
    var_payoff = (s2 - s1 * s1 / ((double)n_paths)) / (n_paths - 1);
    var_control = (s4 - s * s / ((double)n_paths)) / (n_paths - 1);
    cor_payoff_control = cov_payoff_control / (sqrt(var_payoff) * sqrt(var_control));
    control_coef = cov_payoff_control / var_control;
    var_proba = (s6 - s5 * s5 / ((double)n_paths)) / (n_paths - 1);
    *ptprice = exp(beta1 * sigma0 * sqrt(T / n_points)) * (s1 / n_paths - control_coef);
    *priceerror = exp(beta1 * sigma0 * sqrt(T / n_points)) * 1.96 * sqrt(var_payoff);
    *ptdelta = (*ptprice + (K * exp(-r * T) - S0 * exp(-divid * T)) - discount);
    *deltaerror = (*priceerror + discount * s_maxmin * 1.96 * sqrt(var_proba));
}
else//Put
if ((P->Compute) == &Put_OverSpot2)
{
    s_maxmin = MIN(s_maxmin, K);
    s_maxmin = exp(beta1 * sigma0 * sqrt(T / n_points)) * s_maxmin; //shifti
    for (i = 0; i < n_paths; i++)
    {
        //simulation of the positive jump times and number
        tau = -1 / (lambda_p) * log(pnl_rand_uni(generator));
        jump_number_p = 0;
        while (tau < T)
        {
            jump_number_p++;
            jump_time_vect_p[jump_number_p] = tau;
            tau += -1 / (lambda_p) * log(pnl_rand_uni(generator));
        }
        //simulation of the negative jump times and number
        tau = -1 / (lambda_m) * log(pnl_rand_uni(generator));
        jump_number_m = 0;
        while (tau < T)
        {
            jump_number_m++;
            jump_time_vect_m[jump_number_m] = tau;
            tau += -1 / (lambda_m) * log(pnl_rand_uni(generator));
        }
    }
}

```

```

    }
    jump_time_vect_p[jump_number_p + 1] = 0;
    jump_time_vect_m[jump_number_m + 1] = 0;
    //////////////////////////////////////
    // simulation of one NIG path
    for (k = 1; k <= n_points; k++)
    {
        W[k] = sigma0 * pnl_rand_normal(generator) * sqrt(t[k] - t[k - 1]);
        N_p[k] = N_p[k - 1];
        j = N_p[k - 1] + 1;
        while (jump_time_vect_p[j] <= t[k] && j <= jump_number_p)
        {
            N_p[k]++;
            j++;
        }
        s0 = 0;
        for (j = N_p[k - 1] + 1; j <= N_p[k]; j++)
            s0 += jump_generator_NIG(cdf_jump_vect_p, cdf_jump_points, cdf_jump_weights_p[j]);
        N_m[k] = N_m[k - 1];
        j = N_m[k - 1] + 1;
        while (jump_time_vect_m[j] <= t[k] && j <= jump_number_m)
        {
            N_m[k]++;
            j++;
        }
        for (j = N_m[k - 1] + 1; j <= N_m[k]; j++)
            s0 -= jump_generator_NIG(cdf_jump_vect_m, cdf_jump_points, cdf_jump_weights_m[j]);
        X[k] = X[k - 1] + (W[k] - W[k - 1]) + s0;
    }
    //////////////////////////////////////
    //computation of the supremum and the infimum of the CGMY path
    inf = X[0];
    sup = X[0];
    for (j = 1; j <= n_points; j++)
    {
        if (inf > X[j])
            inf = X[j];
        if (sup < X[j])
            sup = X[j];
    }
    proba = 0;

```



```

        infS = S0 * exp(inf);
        if (infS > s_maxmin)
        {
            infS = s_maxmin;
            proba = 1;
        }
        payoff = infS;
        infS = S0 * exp(X[n_points] - sup); //antithetic variable associated
        if (infS > s_maxmin)
        {
            infS = s_maxmin;
            proba += 1.;
        }
        proba = proba / 2;
        payoff = discount * (payoff + infS) / 2;
        control = exp(X[n_points]);
        s += control;
        s1 += payoff;
        s2 += payoff * payoff;
        s3 += control * payoff;
        s4 += control * control;
        s5 += proba;
        s6 += proba * proba;
    }
    cov_payoff_control = s3 / n_paths - s1 * s / ((double)n_paths * n_paths);
    var_payoff = (s2 - s1 * s1 / ((double)n_paths)) / ((double)n_paths - 1);
    var_control = (s4 - s * s / ((double)n_paths)) / ((double)n_paths - 1);
    cor_payoff_control = cov_payoff_control / (sqrt(var_payoff) * sqrt(var_control));
    control_coef = cov_payoff_control / var_control;
    var_proba = (s6 - s5 * s5 / ((double)n_paths)) / ((double)n_paths - 1);
    *ptprice = -exp(-beta1 * sigma0 * sqrt(T / n_points)) * (s1 / (double)n_paths);
    *priceerror = exp(-beta1 * sigma0 * sqrt(T / n_points)) * 1.96 * sqrt(var_payoff);
    *ptdelta = (*ptprice + (S0 * exp(-divid * T) - K * exp(-r * T)) + discount * s_maxmin);
    *deltaerror = (*priceerror + discount * s_maxmin * 1.96 * sqrt(var_proba));
}

free(X);
free(W);
free(cdf_jump_points);
free(cdf_jump_vect_p);
free(cdf_jump_vect_m);
free(jump_time_vect_p);

```

```

    free(jump_time_vect_m);
    free(t);
    free(N_p);
    free(N_m);
    return OK;
}

int CALC(MC_Nig_Fixed)(void *Opt, void *Mod, PricingMethod *Met)
{
    TYPEOPT *ptOpt = (TYPEOPT *)Opt;
    TYPEMOD *ptMod = (TYPEMOD *)Mod;
    double r, divid;

    r = log(1. + ptMod->R.Val.V_DOUBLE / 100.);
    divid = log(1. + ptMod->Divid.Val.V_DOUBLE / 100.);

    return NIG_Mc_Fixed((ptOpt->PathDep.Val.V_NUMFUNC_2)->Par[4].Val.V_PDOUBLE, p
}

static int CHK_OPT(MC_Nig_Fixed)(void *Opt, void *Mod)
{
    if ((strcmp(((Option *)Opt)->Name, "LookBackCallFixedEuro") == 0) || (strcmp((
        return OK;
    return WRONG;
}

#endif //PremiaCurrentVersion
static int MET(Init)(PricingMethod *Met, Option *Mod)
{
    if (Met->init == 0)
    {
        Met->init = 1;
        Met->Par[0].Val.V_ENUM.value = 0;
        Met->Par[0].Val.V_ENUM.members = &PremiaEnumMCRNGs;

        Met->Par[1].Val.V_PINT = 100;
        Met->Par[2].Val.V_LONG = 100000;
    }
    return OK;
}

```

```

PricingMethod MET(MC_Nig_Fixed) =
{
    "MC_NIG_LookbackFixed",
    { {"RandomGenerator", ENUM, {100}, ALLOW},
      {"Number of discretization steps", LONG, {100}, ALLOW}, {"N iterations", LONG, {100}, ALLOW},
    },
    CALC(MC_Nig_Fixed),
    {{"Price", DOUBLE, {100}, FORBID}, {"Delta", DOUBLE, {100}, FORBID}, {"Price Error", DOUBLE, {100}, FORBID}},
    CHK_OPT(MC_Nig_Fixed),
    CHK_ok,
    MET(Init)
} ;

```