

## [Help](#)

```
#include <stdlib.h>
#include "
href../../mod/bs1d/bs1d_std/bs1d_std_h_src.pdfbs1d_std.h"
#include "
href../../common/error_msg_h_src.pdferror_msg.h"
#define PRECISION 1.0e-7 /*Precision for the localization of FD methods*/

static int Explicit(int am, double s, NumFunc_1 *p, double t, double r, double
{
    int i, j, M, Index;
    double h, z, k, p1, p2, p3, l, x, vv, upwind_alphacoef;
    double *S, *P, *Obst;

    /*Memory Allocaction*/
    if (N % 2 == 1) N++;
    S = malloc((N + 1) * sizeof(double));
    if (S == NULL)
        return MEMORY_ALLOCATION_FAILURE;
    P = malloc((N + 1) * sizeof(double));
    if (P == NULL)
        return MEMORY_ALLOCATION_FAILURE;
    Obst = malloc((N + 1) * sizeof(double));
    if (Obst == NULL)
        return MEMORY_ALLOCATION_FAILURE;

    /*Space Localisation*/
    vv = 0.5 * SQR(sigma);
    z = (r - divid) - vv;
    l = sigma * sqrt(t) * sqrt(log(1.0 / PRECISION)) + fabs(z * t);

    /*Space Step*/
    h = 2.*l / (double)N;

    /*Peclet Condition-Coefficient of diffusion augmente*/
    if ((h * fabs(z)) <= vv)
        upwind_alphacoef = 0.5;
    else
    {
        if (z > 0.) upwind_alphacoef = 0.0;
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        else upwind_alphacoef = 1.0;
    }
    vv -= z * h * (upwind_alphacoef - 0.5);

    /*Stability Condition Time Step*/
    k = SQR(h) / (2.*vv + r * SQR(h));
    M = (int)(t / k);

    /*"Probabilities" associated to points*/
    p1 = k * (vv / (SQR(h)) - z / (2.0 * h));
    p2 = 1.0 - k * (2.*vv / SQR(h) + r);
    p3 = k * (vv / (SQR(h)) + z / (2.0 * h));

    /*Terminal Values*/
    x = log(s);
    for (i = 0; i <= N; i++)
    {
        P[i] = (p->Compute)(p->Par, exp(x - 1 + (double)i * h));
        Obst[i] = P[i];
    }

    /*Finite Difference Cycle*/
    for (i = 1; i <= M; i++)
    {
        for (j = 1; j < N; j++)
        {
            S[j] = p1 * P[j - 1] + p2 * P[j] + p3 * P[j + 1];
            /*Splitting for American case*/
            if (am)
                S[j] = MAX(Obst[j], S[j]);
        }
        for (j = 1; j < N; j++)
            P[j] = S[j];
    }

    Index = (int) floor((double)N / 2.0);

    /*Price*/
    *ptprice = P[Index];

    /*Delta*/

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*ptdelta = (P[Index + 1] - P[Index - 1]) / (2.0 * s * h);

/*Memory Desallocation*/
free(S);
free(P);
free(Obst);

return OK;
}

int CALC(FD_Explicit)(void *Opt, void *Mod, PricingMethod *Met)
{
    TYPEOPT *ptOpt = (TYPEOPT *)Opt;
    TYPEMOD *ptMod = (TYPEMOD *)Mod;
    double r, divid;

    r = log(1. + ptMod->R.Val.V_DOUBLE / 100.);
    divid = log(1. + ptMod->Divid.Val.V_DOUBLE / 100.);

    return Explicit(ptOpt->EuOrAm.Val.V_BOOL, ptMod->S0.Val.V_PDOUBLE,
                    ptOpt->PayOff.Val.V_NUMFUNC_1, ptOpt->Maturity.Val.V_DATE - pt
                    r, divid, ptMod->Sigma.Val.V_PDOUBLE, Met->Par[0].Val.V_INT, &

}

static int CHK_OPT(FD_Explicit)(void *Opt, void *Mod)
{
    return OK;
}

static int MET(Init)(PricingMethod *Met, Option *Opt)
{
    if (Met->init == 0)
    {
        Met->init = 1;
        Met->HelpFilenameHint = "fd_explicit_bs";
        Met->Par[0].Val.V_INT2 = 100;

    }

    return OK;
}

```

```
}
```

```
PricingMethod MET(FD_Explicit) =
```

```
{
```

```
    "FD_Explicit",
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```
    {{"TimeStepNumber", INT2, {100}, ALLOW}, {" ", PREMIA_NULLTYPE, {0}, FORBID}},
```

```
    CALC(FD_Explicit),
```

```
    {{"Price", DOUBLE, {100}, FORBID}, {"Delta", DOUBLE, {100}, FORBID} , {" ", PR
```

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    CHK_OPT(FD_Explicit),
```

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    CHK_tree,
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```
    MET(Init)
```

```
};
```