

[Help](#)

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#include <stdlib.h>
#include "
href../../mod/mer1d/mer1d_std/mer1d_std_h_src.pdfmer1d_std.h"
#include "
href../../common/enums_h_src.pdfenums.h"

#if defined(PremiaCurrentVersion) && PremiaCurrentVersion < (2007+2) //The "#els
static int CHK_OPT(FD_AndersenAndreasen)(void *Opt, void *Mod)
{
    return NONACTIVE;
}
int CALC(FD_AndersenAndreasen)(void *Opt, void *Mod, PricingMethod *Met)
{
    return AVAILABLE_IN_FULL_PREMIA;
}
#else

static int asym_1d(int am, PARAM p, DENSITY g, MESH m, WEIGHT w, IMESH Im, NumFu
{
    int j, i, ii;
    unsigned long n2;
    double dum, *data, *sol_a, *sol_b, *p1, *p2, *p3, *tnoto, *boundary, *ftg, *ff

    n2 = m.N << 1;
    /* vector allocation */
    sol_a = malloc((m.N + 1) * sizeof(double));
    if (sol_a == NULL) return MEMORY_ALLOCATION_FAILURE;
    memset(sol_a, 0, (m.N + 1)*sizeof(double));
    Obst = malloc((m.N + 1) * sizeof(double));
    if (Obst == NULL) return MEMORY_ALLOCATION_FAILURE;
    memset(Obst, 0, (m.N + 1)*sizeof(double));
    sol_b = malloc((m.N + 1) * sizeof(double));
    if (sol_b == NULL) return MEMORY_ALLOCATION_FAILURE;
    memset(sol_b, 0, (m.N + 1)*sizeof(double));
    tnoto = malloc((n2 + 1) * sizeof(double));
    if (tnoto == NULL) return MEMORY_ALLOCATION_FAILURE;
    memset(tnoto, 0, (n2 + 1)*sizeof(double));
    p1 = malloc((m.N + 1) * sizeof(double));
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if (p1 == NULL) return MEMORY_ALLOCATION_FAILURE;
memset(p1, 0, (m.N + 1)*sizeof(double));
p2 = malloc((m.N + 1) * sizeof(double));
if (p2 == NULL) return MEMORY_ALLOCATION_FAILURE;
memset(p2, 0, (m.N + 1)*sizeof(double));
p3 = malloc((m.N + 1) * sizeof(double));
if (p3 == NULL) return MEMORY_ALLOCATION_FAILURE;
memset(p3, 0, (m.N + 1)*sizeof(double));
data = malloc((m.N + 3) * sizeof(double));
if (data == NULL) return MEMORY_ALLOCATION_FAILURE;
memset(data, 0, (m.N + 3)*sizeof(double));
boundary = malloc((m.N) * sizeof(double));
if (boundary == NULL) return MEMORY_ALLOCATION_FAILURE;
memset(boundary, 0, (m.N)*sizeof(double));
fftg = malloc((n2 + 1) * sizeof(double));
if (fftg == NULL) return MEMORY_ALLOCATION_FAILURE;
memset(fftg, 0, (n2 + 1)*sizeof(double));
ftg = malloc((m.N + 3) * sizeof(double));
if (ftg == NULL) return MEMORY_ALLOCATION_FAILURE;
memset(ftg, 0, (m.N + 3)*sizeof(double));
g.d = malloc((m.N + 1) * sizeof(double));
if (g.d == NULL) return MEMORY_ALLOCATION_FAILURE;
for (j = 1; j <= m.N; j++) ftg[j] = (g.d)[j] = 1.0 / (sqrt(2.0 * M_PI * g.par2

/* FFT of the density function */
drealft(ftg, m.N, 1);

/*Terminal Values*/
for (j = 1; j <= m.N; j++)
{
    boundary[j - 1] = sol_a[j] = (p_func->Compute)(p_func->Par, exp(m.xmin + (
    Obst[j] = sol_a[j];
}

/* boundary */
set_boundaryAA(bound, m, p, Im, boundary, boundary);

/* "Probabilities" associated to points */
for (j = 1; j <= Im.min; j++)
{
    p1[j] = 0.;

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        p2[j] = 1.0;
        p3[j] = 0.;
    }
    for (j = Im.min; j <= Im.max; j++)
    {
        p1[j] = -m.k / 2.0 * w.p1;
        p2[j] = 1.0 + m.k / 2.0 * w.p2;
        p3[j] = -m.k / 2.0 * w.p3;
        /*
            p1[j]= -m.k*w.p1;
            p2[j]= 1.0+m.k*w.p2;
            p3[j] = -m.k*w.p3;
        */
    }
    for (j = Im.max + 1; j <= m.N; j++)
    {
        p1[j] = 0.;
        p2[j] = 1.0;
        p3[j] = 0.;
    }
    /* Finite Difference Cycle */
    for (i = 1; i <= m.M; i++)
    {

        /* step 1 */
        for (j = 1; j <= Im.min; j++)
        {
            data[j] = boundary[j - 1]; /* boundary */
        }
        for (j = Im.max + 1; j <= m.N; j++)
        {
            data[j] = boundary[j - 1]; /* boundary */
        }
        for (j = Im.min; j < Im.max; j++)
        {
            data[j] = sol_a[j];
        }

        /* okcorrel=dcorrel(data,g.d,m.N,tnoto);
            if (okcorrel != RETURNOK) return okcorrel; */
        /* -- */
    }

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drealft(data, m.N, 1);
for (ii = 2; ii <= m.N + 2; ii += 2)
{
    tnoto[ii - 1] = (data[ii - 1] * (dum = ftg[ii - 1]) + data[ii] * ftg[i
    tnoto[ii] = (data[ii] * dum - data[ii - 1] * ftg[ii]) / (m.N / 2);
}
tnoto[2] = tnoto[m.N + 1];
drealft(tnoto, m.N, -1);

for (j = 1; j <= Im.min; j++)
{
    data[j] = boundary[j - 1]; /* boundary */
}
for (j = Im.max; j <= m.N; j++)
{
    data[j] = boundary[j - 1]; /* boundary */
}
/* -- */

for (j = Im.min; j < Im.max; j++)
{
    data[j] = m.k / 2.*w.p1 * sol_a[j - 1] + (1.0 - m.k / 2.*w.p2) * sol_a
    /* data[j]=sol_a[j]+m.k/2.0*p.lambda*m.h*tnoto[j-Im.min+1]; */
}
/* tridiagonal system */
tridiag_bis(p1, p2, p3, data, sol_b, m.N);

/* step 2 */
/*
    data[0]=boundary[0];
    for (j=1;j<=m.N-1;j++){
        data[j]=m.k/2.*w.p1*sol_b[j-1]+(1.0-m.k/2.*w.p2)*sol_b[j]+m.k/2.*w.p3*
    }
    data[m.N-1]=boundary[m.N-1];

    dtwofft(data-1,g.d-1,tnoto-1,fftg-1,m.N);
    for (j=1;j<=m.N+2;j+=2){
        r = tnoto[j-1]*(1-m.k/2.*p.lambda*fftg[j-1])-tnoto[j]*m.k/2.*p.lambda*
        im = tnoto[j-1]*m.k/2.*p.lambda*fftg[j]+tnoto[j]*(1-m.k/2.*p.lambda*ff
        den = SQR(1-m.k/2.*p.lambda*fftg[j-1])+SQR(m.k/2.*p.lambda*fftg[j]);
        fftg[j-1] = r/(den);

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        fftg[j] = im/(den);
    }
    fftg[1]=fftg[m.N];
    drealft(fftg-1,m.N,-1);
*/
for (j = 0; j < m.N; j++)
{
    sol_a[j] = sol_b[j];
    /* sol_a[j]=2.0/m.N*fftg[j]; */
    if (am)
        sol_a[j] = MAX(Obst[j], sol_a[j]);
}
}

/* Price */
*ptprice = sol_a[m.Index + 1];
/*Delta*/
*ptdelta = (sol_a[m.Index + 1] - sol_a[m.Index - 1]) / (2.0 * p.s * m.h);

/* Memory Desallocation */
free(sol_a);
free(sol_b);
free(p1);
free(p2);
free(p3);
free(tnoto);
free(data);
free(boundary);
free(g.d);
free(fftg);
free(ftg);
free(Obst);

return RETURNOK;
}
static int AndersenAndreasen(int am, double s, NumFunc_1 *p_func, double t, dou
{
    MESH m;
    WEIGHT w;
    IMESH Im;

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PARAM p;
DENSITY g;
EQ eq;
double K;

K = p_func->Par[0].Val.V_DOUBLE;
Gaussian_data(mu, gamma2, &g);
set_parameter(s, K, t, r, sigma, divid, lambda, g.Eu, &p);
equation(p, &eq);

if (N % 2 == 1) N++;

initgrid_1Dbis(p, g, eq, N, &m, &Im);
set_weights_impl(M, p.T, eq, &m, &w);
/* Gaussian_vect(0,Im.N,m.h,&g); */
asym_1d(am, p, g, m, w, Im, p_func, bound, ptprice, ptdelta);

/*    freeDensity(&g); */

return OK;
}

int CALC(FD_AndersenAndreasen)(void *Opt, void *Mod, PricingMethod *Met)
{
    TYPEOPT *ptOpt = (TYPEOPT *)Opt;
    TYPEMOD *ptMod = (TYPEMOD *)Mod;
    double r, divid;

    r = log(1. + ptMod->R.Val.V_DOUBLE / 100.);
    divid = log(1. + ptMod->Divid.Val.V_DOUBLE / 100.);

    return AndersenAndreasen(ptOpt->EuOrAm.Val.V_BOOL,
                             ptMod->SO.Val.V_PDOUBLE,
                             ptOpt->PayOff.Val.V_NUMFUNC_1,
                             ptOpt->Maturity.Val.V_DATE - ptMod->T.Val.V_DATE,
                             r,
                             divid,
                             ptMod->Sigma.Val.V_PDOUBLE,
                             ptMod->Lambda.Val.V_PDOUBLE,
                             ptMod->Mean.Val.V_PDOUBLE,
                             ptMod->Variance.Val.V_PDOUBLE,

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        Met->Par[0].Val.V_INT,
        Met->Par[1].Val.V_INT,
        Met->Par[2].Val.V_ENUM.value,
        &(Met->Res[0].Val.V_DOUBLE),
        &(Met->Res[1].Val.V_DOUBLE));
    }

static int CHK_OPT(FD_AndersenAndreasen)(void *Opt, void *Mod)
{
    /*
     *   Option* ptOpt=(Option*)Opt;
     *   TYPEOPT* opt=(TYPEOPT*)(ptOpt->TypeOpt);
     */
    return OK;
}

#endif //PremiaCurrentVersion

static int MET(Init)(PricingMethod *Met, Option *Opt)
{
    if (Met->init == 0)
    {
        Met->init = 1;

        Met->Par[0].Val.V_INT2 = 8192;
        Met->Par[1].Val.V_INT2 = 500;
        Met->Par[2].Val.V_ENUM.value = 0;
        Met->Par[2].Val.V_ENUM.members = &PremiaEnumBoundaryCond;
    }

    return OK;
}

PricingMethod MET(FD_AndersenAndreasen) =
{
    "FD_AndersenAndreasen",
    { {"SpaceStepNumber MUST be an integer power of 2 (this is not checked for!)",
        {"TimeStepNumber", INT2, {100}, ALLOW},
        {"Boundary Condition", ENUM, {1}, ALLOW},

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    {" ", PREMIA_NULLTYPE, {0}, FORBID}
},
CALC(FD_AndersenAndreasen),
{"Price", DOUBLE, {100}, FORBID}, {"Delta", DOUBLE, {100}, FORBID}, {" ", PRE
CHK_OPT(FD_AndersenAndreasen),
CHK_split,
MET(Init)
};

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