

[Help](#)

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#include "
href../../mod/bs1d/bs1d_std/bs1d_std_h_src.pdfbs1d_std.h"
#include <stdlib.h>

#define CALLOC_1D(P,N)  P=(double*)calloc(N+1,sizeof(double));\
    if (P==NULL)\
        return 1;\

#define CALLOC_2D(P,N)  P=(double**)calloc(N+1,sizeof(double*));\
    if (P==NULL)\
        return 1;\
    for (i=0;i<N+1;i++)\
    {\
        P[i]=(double*)calloc(N+1,sizeof(double));\
        if (P[i]==NULL)\
return 1;\
    }\

#define DESALLOC_2D(P,N)  for (i=0;i<N+1;i++)\
    free(P[i]);\
    free(P)\

#define DESALLOC_1D(P,N)  free(P)

static int CoxPatry_98(double s, NumFunc_1 *p, double t, double r, double divid,
{
    int i, iStar, j, k, n;
    double u, d, pu, pd, a1, price = 0., stock, lowerstock, h;
    double **Spot, **Price, **CurrentVStar, **PrevVStar;
    double *SqrSpot, *SqrPrice, *SpotPrice, *CurrentV;
    double alpha, alpha_step, alphaStar, obstacle_value, current_value, price_minu

    /*Price, Variance arrays*/
    CALLOC_2D(Spot, N);
    CALLOC_2D(Price, N);
    CALLOC_2D(CurrentVStar, N);
    CALLOC_2D(PrevVStar, N);

    CALLOC_1D(CurrentV, N);
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CALLOC_1D(SqrSpot, N);
CALLOC_1D(SqrPrice, N);
CALLOC_1D(SpotPrice, N);

/*Up and Down factors*/
h = t / (double)N;
a1 = exp(h * (r - divid));
u = exp(sigma * sqrt(h));
d = 1. / u;

/*Risk-Neutral Probability*/
pu = (a1 - d) / (u - d);
pd = 1. - pu;

/*FirstStep: Spot, Price, VStarZero (PrevVStar) computation*/
/*Price initialisation*/
lowerstock = s;
for (i = 0; i < N; i++)
    lowerstock *= d;

stock = lowerstock * exp(-r * t);

for (i = 0; i <= N; i++)
{
    price = Price[N][i] = (p->Compute)(p->Par, stock * exp(r * t)) * exp(-r * t);

    Spot[N][i] = stock;
    SqrSpot[i] = stock * stock;
    SqrPrice[i] = price * price;
    SpotPrice[i] = stock * price;
    stock *= (u / d);
}

/*Backward Resolution*/
for (i = N - 1; i >= 0; i--)
    for (j = 0; j <= i; j++)
    {
        price = Price[i][j] = pu * Price[i + 1][j + 1] + pd * Price[i + 1][j];
        stock = Spot[i][j] = pu * Spot[i + 1][j + 1] + pd * Spot[i + 1][j];
        SqrSpot[j] = pu * SqrSpot[j + 1] + pd * SqrSpot[j];
        SqrPrice[j] = pu * SqrPrice[j + 1] + pd * SqrPrice[j];
    }

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        SpotPrice[j] = pu * SpotPrice[j + 1] + pd * SpotPrice[j];

        PrevVStar[i][j] = SqrPrice[j] - price * price - \
            (SpotPrice[j] - price * stock) * (SpotPrice[j] - price
    }

alphaStar0 = (SpotPrice[0] - price * stock) / (SqrSpot[0] - stock * stock);

iStar = 1;

alphaStar = alphaStar0;

/*SecondStep: Vstar_n computation*/
alpha_step = (alpha_max - alpha_min) / (double)N_Sample;

if (N_Hedge == 0)
{
    iStar = 1;
    CurrentVStar[0][0] = PrevVStar[0][0];
}
else
{
    if (N == N_Hedge)
    {
        iStar = 0;
        alphaStar = (Price[1][1] - Price[1][0]) * exp(r * h) / (s * (u - d));
        CurrentVStar[0][0] = 0.;
    }
    else
    {
        if (PrevVStar[0][0] == 0.)
        {
            iStar = 0;
            CurrentVStar[0][0] = 0.;
        }
        else
        {
            for (n = 1; n <= N_Hedge; n++)
            {
                alpha = alpha_min;
                if (n < N_Hedge)

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alphaStar = alpha_min;
for (k = 0; k <= N_Sample; k++)
{
    /*CurrentV Initialisation*/
    for (j = 0; j <= N - n; j++)
    {
        price_minus_alpha_spot = Price[N - n][j] - alpha * Spot
        CurrentV[j] = price_minus_alpha_spot * price_minus_alp
    }

    /*We start the computation at time N-n-1*/
    for (i = N - n - 1; i >= 0; i--)
        for (j = 0; j <= i; j++)
        {
            CurrentV[j] = pu * CurrentV[j + 1] + pd * CurrentV[j]
            price_minus_alpha_spot = Price[i][j] - alpha * Spot
            obstacle_value = price_minus_alpha_spot * price_minu

            if (CurrentV[j] > obstacle_value)
            {
                if ((n == N_Hedge) && (alpha == alphacourant) &&
                    iStar = 0;
                CurrentV[j] = obstacle_value;
            }

            /*Compute the new current minimum of V_n(alpha)*/
            current_value = CurrentV[j] - price_minus_alpha_spot
            if (k > 0)
            {
                if (CurrentVStar[i][j] > current_value)
                {
                    if ((n == (N_Hedge - 1)) && (i == 0))
                        alphaStar = alpha;
                    CurrentVStar[i][j] = current_value;
                }
            }
            else CurrentVStar[i][j] = current_value;
        } /*End j*/
    alpha += alpha_step;
} /*End k*/

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        for (i = N - n - 1; i >= 0; i--)
            for (j = 0; j <= i; j++)
                PrevVStar[i][j] = CurrentVStar[i][j];
    }/*End n*/
    }
}

if (PrevVStar[0][0] < 1.0e-7)
    alphaStar = alphaStar0;

*ptprice = Price[0][0];
*ptdelta = alphaStar;
*ptvariance = CurrentVStar[0][0];
*pthedge = !(iStar == 0); /*pthedge=0 means it's optimal to hedge*/

DESALLOC_1D(SqrSpot, N);
DESALLOC_1D(SqrPrice, N);
DESALLOC_1D(SpotPrice, N);
DESALLOC_1D(CurrentV, N);

DESALLOC_2D(Spot, N);
DESALLOC_2D(Price, N);
DESALLOC_2D(CurrentVStar, N);
DESALLOC_2D(PrevVStar, N);

return 0;
}

int CALC(TR_Patry)(void *Opt, void *Mod, PricingMethod *Met)
{
    TYPEOPT *ptOpt = (TYPEOPT *)Opt;
    TYPEMOD *ptMod = (TYPEMOD *)Mod;
    double r, divid, alphamin, alphamax;

    r = log(1. + ptMod->R.Val.V_DOUBLE / 100.);

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divid = log(1. + ptMod->Divid.Val.V_DOUBLE / 100.);

alphamin = -1.;
alphamax = 1.;

return CoxPatry_98(ptMod->S0.Val.V_PDOUBLE,
                   ptOpt->PayOff.Val.V_NUMFUNC_1, ptOpt->Maturity.Val.V_DATE -
                   r, divid, ptMod->Sigma.Val.V_PDOUBLE,
                   Met->Par[0].Val.V_INT2, Met->Par[1].Val.V_INT, Met->Par[3].
                   alphamin, alphamax,
                   &(Met->Res[2].Val.V_DOUBLE), &(Met->Res[0].Val.V_DOUBLE),
                   &(Met->Res[1].Val.V_DOUBLE), &(Met->Res[3].Val.V_BOOL),
                   Met->Par[2].Val.V_DOUBLE);
}

static int CHK_OPT(TR_Patry)(void *Opt, void *Mod)
{
    Option *ptOpt = (Option *)Opt;
    TYPEOPT *opt = (TYPEOPT *) (ptOpt->TypeOpt);

    if ((opt->EuOrAm). Val.V_BOOL == EURO)
        return OK;

    return WRONG;
}

static int MET(Init)(PricingMethod *Met, Option *Opt)
{
    if (Met->init == 0)
    {
        Met->init = 1;

        Met->Par[0].Val.V_INT2 = 100; /*stepnumber*/
        Met->Par[1].Val.V_INT = 10; /*hedgenumber*/
        Met->Par[2].Val.V_DOUBLE = 0.; /*currentdelta*/
        Met->Par[3].Val.V_INT2 = 100; /*hedgesampling*/

        Met->Res[0].Val.V_DOUBLE = 0.; /*optimaldelta*/
        Met->Res[1].Val.V_DOUBLE = 0.; /*variance*/
    }
}

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        Met->Res[2].Val.V_DOUBLE = 0.; /*optimalprice*/
        Met->Res[3].Val.V_BOOL = 0; /*hedgenow*/

    }

    return OK;
}

PricingMethod MET(TR_Patry) =
{
    "TR_Patry",
    {
        {"StepNumber", INT2, {100}, ALLOW},
        {"HedgeNumber", INT, {10}, ALLOW},
        {"CurrentDelta", DOUBLE, {10}, IRRELEVANT},
        {"HedgeSampling", INT2, {100}, ALLOW},

        {" ", PREMIA_NULLTYPE, {0}, FORBID}
    },
    CALC(TR_Patry),
    {
        {"OptimalDelta", DOUBLE, {100}, FORBID} ,
        {"Variance", DOUBLE, {100}, FORBID},
        {"OptimalPrice", DOUBLE, {100}, FORBID} ,
        {"HedgeNow", BOOL, {0}, FORBID} ,
        {" ", PREMIA_NULLTYPE, {0}, FORBID}
    },
    CHK_OPT(TR_Patry),
    CHK_tree,
    MET(Init)
};

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